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Non-compliance with the specification might cause risk for life or health and can determine proper work of the blind. We strongly recommend to comply with the specification.

1. General information



35 LE motor with battery and radio receiver

LE type motors equipped with a radio receiver are wireless and can be controlled with a remote. They are designed for automation of blinds. They have electronic limit switches which are programmed by the remote control. Built-in battery makes it easy to mount the drive without having to supply power. LE type motores are compatible with all YOODA transmitters.

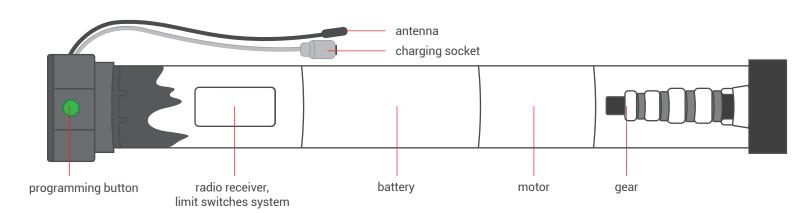
Radio receiver memory: up to 10 transmitters

Power supply: 12 V DC

Operating temperature: from -5°C to 50°C

Protection degree: IP 40

Load: 35LE 3 Nm up to 7 kg 35LE 10 Nm up to 24 kg





Programming button functions:

- 1. Pressing the programming button briefly for approximately 1 second controls the drive step by step. The function is active after the limit positions have been programmed.
- 2. Press the programming button for 2 seconds to enter the transmitter programming mode.
- 3. Pressing the programming button for 6 seconds block radio signal. To turn off this function, briefly press the programming button on the motor head.
- 4. Pressing the programming button for 10 seconds changes work motor direction.
- 5. Pressing the programming button for 14 seconds deletes the motor memory and restores the factory settings.

2. Safety measures

Before installing or using motor please read the following instruction. The installer must comply with the standards and regulations in force in the country where the appliance will be installed and provide information to users about the conditions and maintenance of the device. Failure to follow these instructions can present risk to life and health, or invalid functioning of the roller shutter. This also results in the loss of warranty rights.



Motors torque parameter should be adequate to the weight of the roller shutter curtain.



Do not hit the motor. Reduce the vibration of the motor to a minimum.



No tools should be used when placing motor in the tube.



During the adapter montage special attention must be paid not to damage the motor.



All contact of the motor with any liquids should be reduced to minimum.



Motor and its control system should be kept out of children reach.



Motor cables should be installed in such a way that water can not get inside to the motor and that they have not been damaged by working roller shutter.

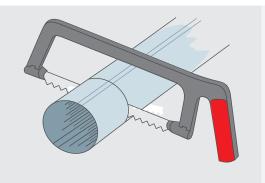


Electrical system control should be performed regularly to detect any signs of use or damage of the motor.

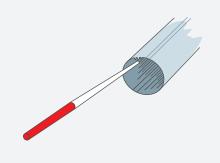
3. Placing motor in the tube



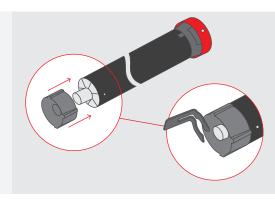
Motor should be mounted in places protected from unfavourable weather conditions. Do not pull the motor head when removing it from the tube.



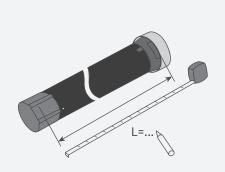
1. Cut the tube to the proper length.



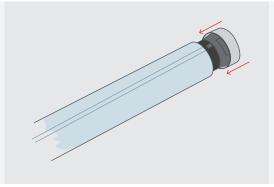
2. Deburr the edges



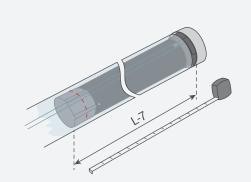
3. Place the adaptation



Measure the distance (L)
between the inner edge of motors head
and the end of the motors adaptor.



5. Insert the motor into the tube up to the point of connection between the edge of the tube and the inner edge of the motors head.

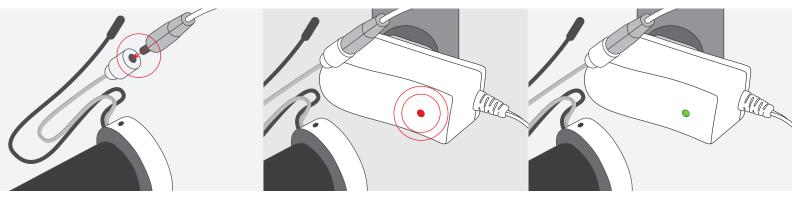


Attach the tube to the coupling part of the adaptation.

4. Charging



- 1. It is recommended to charge the battery by min. 3 hours.
- 2. Ensure that the drive is fully charged before initial startup.
- 3. Charge the battery at least once every 6 months.
- 4. Use only power supply, dedicated to the device. Using another power supply may damage the motor.
- 5. If the supply voltage falls below 10 V, the motor signals the need to charge the battery by making a 10 sounds.



Connect the motor to the power supply

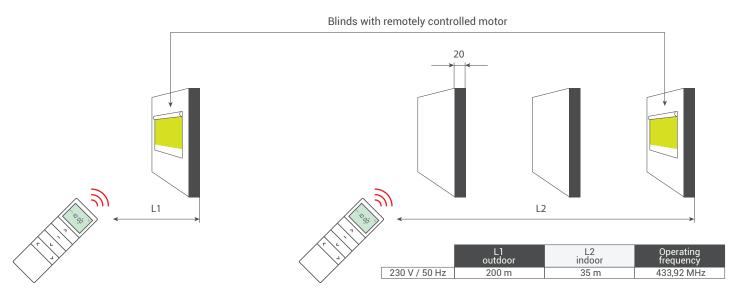
During charging, the LED diode on the power supply light is red.

When the battery is fully charged, the LED diode will turn to green.

5. Range



Radio receiver range is a variable value and can differ from declared values depending on conditions in which device operates. Possible sources of changes in range are building construction, interference caused by other radio transmitters etc.

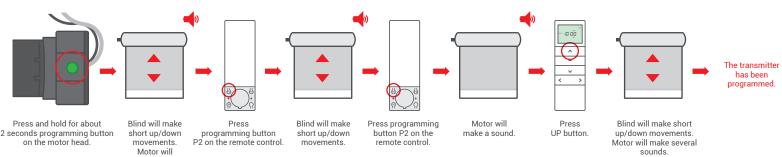


6. Programming first transmitter

make a sound.



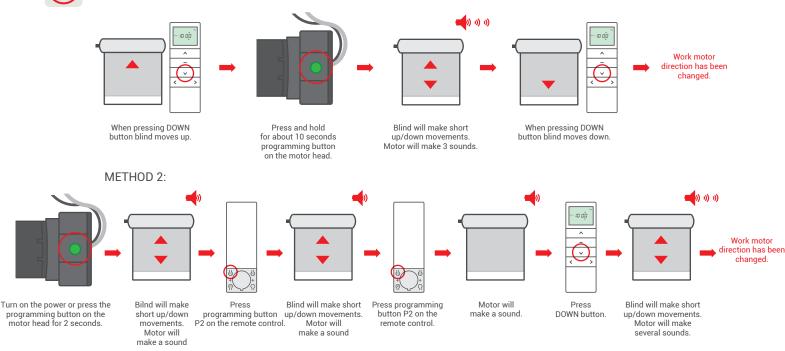
Longer than 10 seconds pause between series of button clicks during programming will cause device to switch off from programming mode without saving any changes.



7. Changing motors direction



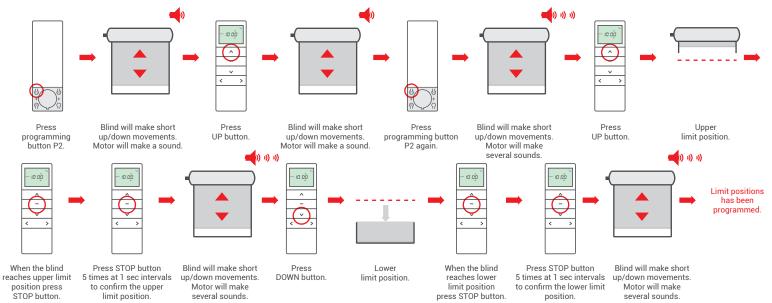
We can change the work direction of the motor by using two methods: METHOD 1:



8. Programming limit positions



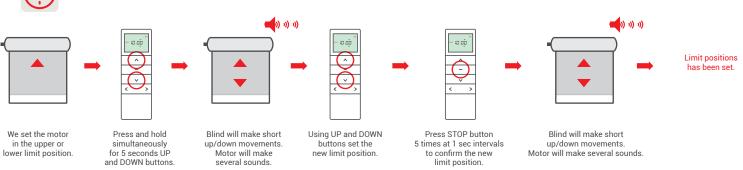
To set the upper and lower limit position press the programming button P2 during the motor movement, it causes the work displacement. Then you can precisely set the limit positions. Pressing the P2 button again motor will run continuously.

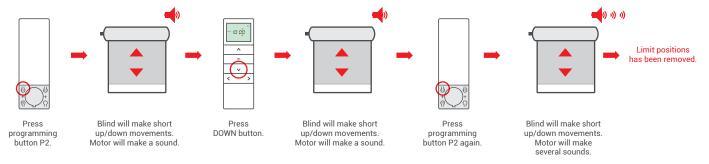


9. Regulation limit positions



In case of setting the limit positions, the upper or lower limit position can be corrected.

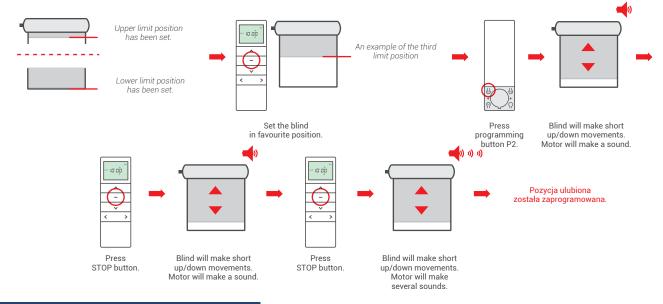




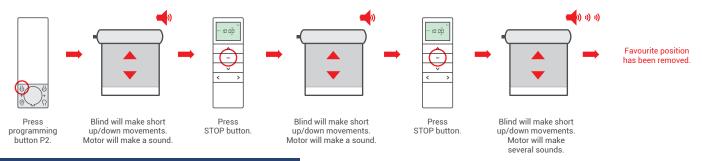
11. Programming the third limit position



- 1. After setting the upper and lower limit positions, it is possible to set the third position (favorite) between those positions.
- 2. Hold the STOP button for 3 seconds to set the blind in third limit position.
- 3. When the motor is in pulse mode, hold the STOP button for 3 seconds, blind reaches lower limit position, and then to the set third position.



12. Removing third limit position



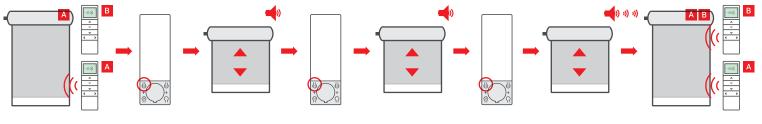
13. Programming another transmitter



Receiver can be controlled by up to 10 transmitters.

Longer than 10 seconds pause between series of button clicks during programming will cause device to switch off from programming mode without saving any changes.

METHOD 1:

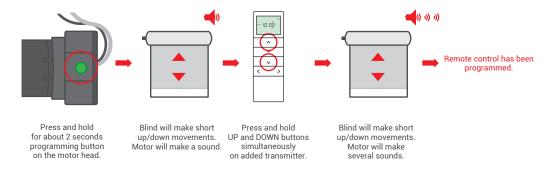


Press programming button P2 on the

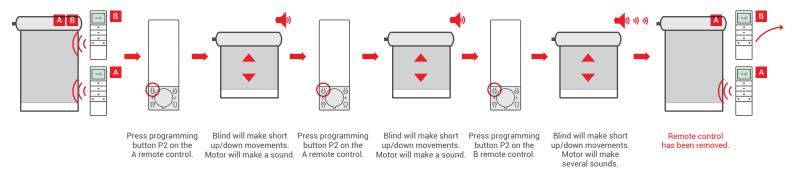
Blind will make short up/down movements. Motor will make a sound.

Press programming button P2 on the A remote control. Blind will make short up/down movements. Motor will make a sound.

t Press programming s. button P2 on the nd. B remote control. Blind will make short up/down movements. Motor will make several sounds. Remote control has been programmed.



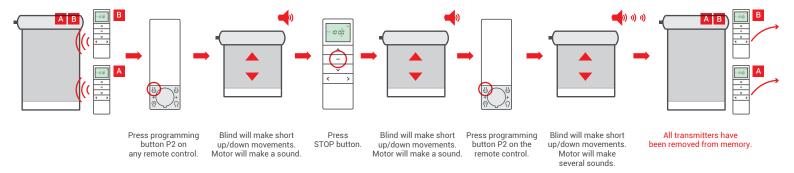
14. Deleting another transmitter



15. Deleting motor memory



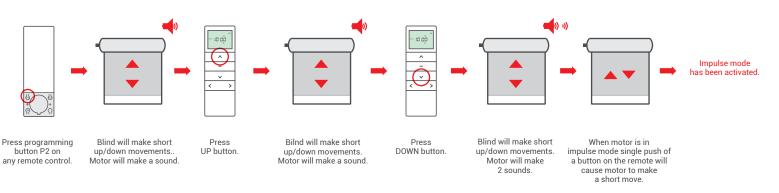
Deleting memory of motors radio receiver will cause for all programmed transmitters to be lost. Longer than 10 seconds pause between series of button clicks during programming will cause device to switch off from programming mode without saving any changes.



16. Activating impulse mode



- 1. Longer than 10 seconds pause between series of button clicks during programming will cause device to switch off from programming mode without saving any changes.
- 2. To activate impulse mode please make the procedure below. To reverse this procedure please repeat the instruction.



17. Programming key-ring remotes



When transmitters do not have a programming button, the STOP + UP buttons' combination perform the programming function.

Longer than 10 seconds pause between series of button clicks during programming will cause device to switch off from programming mode without saving any changes.

