DC265
Receiver Specification

Version NO. : A/00

T Receiver specification
Technical support

DC265 Receiver

①DC265 applied for max 50N.m tubular motor
②When connected to the external switch , by the wire jumper function in setting , you can use it.
③Working temperature：-5~50℃
④Maximum load power：800W

⚠ ① When emitter is under group control, match code will be invalid.
② When receiver is in dot-move mode, press up or down button within 2 seconds, motor will be controlled to operate in Dot-move mode; if keep pressing over 2 seconds, motor will continuously work.
③Motor controlled by DC381F will stop automatically after running for 3 min

T Control range
Technical support
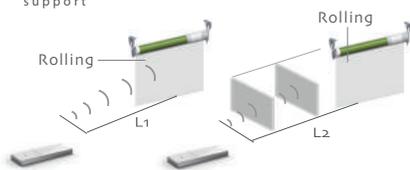
⚠ Effective transmitting distancemay have deviation due to actual environment

Rolling
Rolling
L1
L2

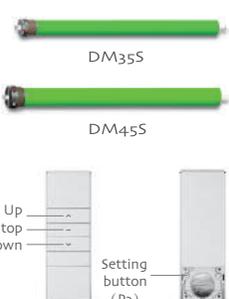|	L1 open	L2 partition	📶 Emission frequency
120V/60Hz	200m	35m	433.92MHz
230V/50Hz	200m	35m	433.92MHz

T Matchable emitter
Technical support

⚠ For the emitters without set button like DC316, you can press up button and stop button at the same time to work as the same function as set button.

DC305A Single-channel emitter
DC306A Five-channel emitter
DC307A Nine-channel emitter
DC61 Miniaturised portable emitter
DC115A Miniaturised portable emitter
DC1600 Single-channel emitter
DC1602 Fifteen-channel emitter

DC287 Single-channel emitter
DC288 Five-channel emitter
DC289 Fifteen-channel emitter
DC262 Fifteen-channel emitter
DC316 Portable double-channel wall-mounted emitter
DC476 Portable nine-channel emitter
DC1653 15-channel LCD emitter

Matchable Motor and emitter
DM35S
DM45S

Up
Stop
Down
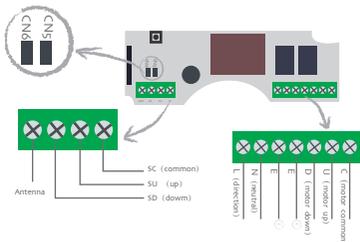Setting button (P2)

T Mode of connection
Technical support

⚠ When connected to the external switch , by the wire jumper function in setting , you can use it.
(wire jumper is to use mini jumper to set short circuit)

The motor stops automatically in the switching mode as below:
①no wire jumper, beep once;press switch button, and the motor starts;release the button, the motor stops.
②wire jumper in CN5,beep twice; press up button, motor is upward; press down button, motor stops at first; press again, motor is downward.
③wire jumper in CN6,beep three times,press up button, motor is upward; press down button, motor is downward. When upward, if press the up button, motor stops and so as to the downward operation.
④ wire jumper in CN5+CN6,beep four times; press the switch button,release it after 2 seconds, the motor continue to operates.
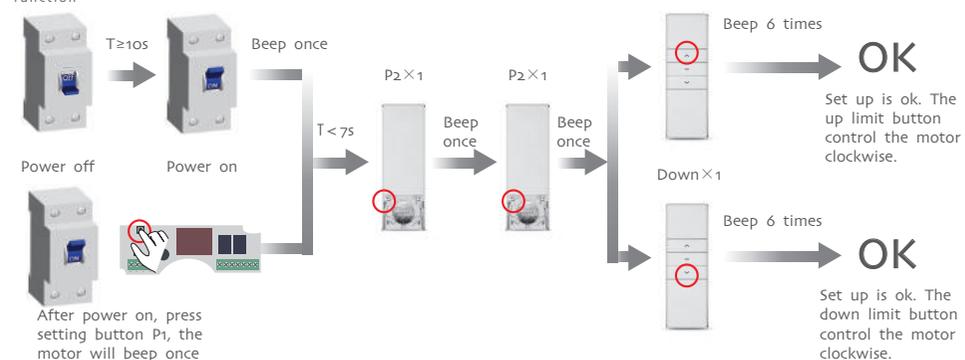
CN5
CN6
Antenna
SC (common)
SU (up)
SD (down)
L (direction)
N (neutral)
E
D (motor down)
U (motor up)
C (motor common)

The best installation distance
1 The shortest distance between receiver and ground ≥1.5m
2 The shortest distance between receiver and roof ≥0.3m
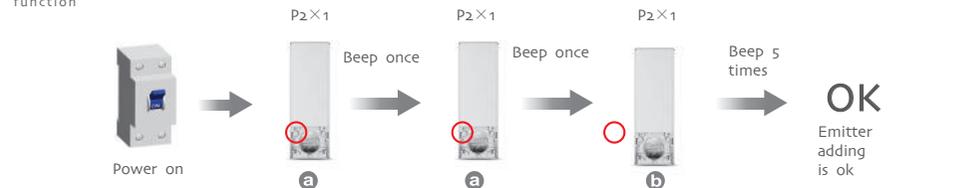3 The shortest distance between receiver and receiver ≥0.2m
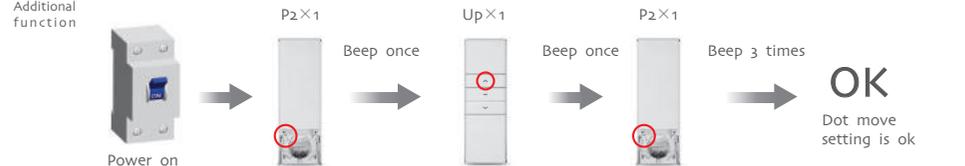

A Set up
Additional function

During the settings, the time between two operation must be shorter than 4s, otherwise it will quit the setting

⚠ If the motor already experienced match code, the memory will be cleared if do it again

Power off → Power on
T≥10s
Beep once
T<7s

After power on, press setting button P1, the motor will beep once

P2×1 → Beep once → P2×1 → Beep once

Up×1 → Beep 6 times → OK
Set up is ok. The up limit button control the motor clockwise.

Down×1 → Beep 6 times → OK
Set up is ok. The down limit button control the motor clockwise.

A Add Emitter
Additional function

⚠ Emitter a is the one already matched code, while emitter b has not

Power on (a) → P2×1 → Beep once → P2×1 (a) → Beep once → P2×1 (b) → Beep 5 times → OK
Emitter adding is ok

A Dot-move setting
Additional function

⚠ Repeat setting, function is cancelled

Power on → P2×1 → Beep once → Up×1 → Beep once → P2×1 → Beep 3 times → OK
Dot move setting is ok

A Delete all the emitter channels
Additional function

Power on → P2×1 → Beep once → Stop×1 → Beep once → P2×1 → Beep 4 times → OK
Deleting all the emitters